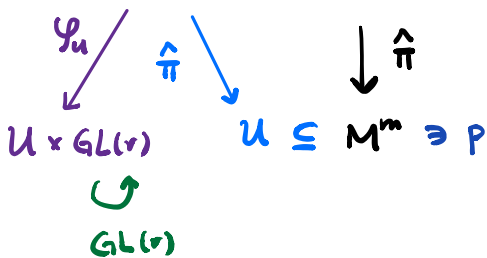


# MATH 5061 Lecture on 3/11/2020

Recall:  $\pi: E \rightarrow M^m$  vector bundle, one consider

"frame bundle"  $GL(r)$

$$\hat{\pi}^{-1}(u) \subseteq F(E) \ni (p, \underline{\xi}) \quad \text{where } \underline{\xi} = (S_1, \dots, S_r) \text{ basis for } E_p$$



This is an example of "Principal  $GL(r)$ -bundle":

- $\exists$  free right  $GL(r)$ -action on  $F(E)$  by "change of basis":

$$A \in GL(r) \Rightarrow R_A: F(E) \rightarrow F(E)$$

$$R_A(p, \underline{\xi}) = (p, \underline{\xi} A)$$

- locally,  $\exists$  trivialization

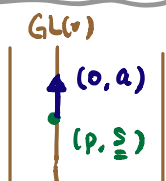
$$\psi_u: \hat{\pi}^{-1}(u) \xrightarrow{\cong} U \times GL(r)$$

s.t. it's "compatible" with  $GL(r)$ -action

$$\psi_u(p, \underline{\xi}) = (p, B)$$

$$\psi_u(R_A(p, \underline{\xi})) = (p, BA)$$

More generally, consider principal  $G$ -bundle for any Lie group  $G$



$$\hat{\omega} \in \Omega^1(F(E)) \otimes \mathfrak{gl}(r)$$

$$F(E) \xrightarrow{R_A}$$

$M$

Thm: A connection  $D$  on  $\pi: E \rightarrow M$

$\Leftrightarrow$

A connection 1-form  $\hat{\omega}$  on  $F(E)$  with values in  $\mathfrak{gl}(r) = \{r \times r \text{ matrices}\} =$  Lie algebra of  $GL(r)$

locally:  $\omega = (\omega_j^i)$   
1-forms matrix-valued on  $M$

$$\text{s.t. (1) } \hat{\omega}(0, a) = a \quad \forall (0, a) \in T_{(p, \underline{\xi})} F(E)$$

$$(2) R_A^* \hat{\omega} = A^{-1} \hat{\omega} A \quad \forall A \in GL(r)$$

Proof: " $\Leftarrow$ " Exercise.

" $\Rightarrow$ " Given  $D$  on  $\pi: E \rightarrow M$ , GOAL: Construct  $\hat{\omega}$  satisfying (1) & (2).

$F(E)$   $\hat{\pi}^*(\omega_u)$  Locally, fix local basis  $\underline{\xi}_u = (S_1^u, \dots, S_r^u)$  of  $E$  over  $u \subseteq M$ .

$\downarrow \hat{\pi} \quad \uparrow \hat{\pi}^* \rightsquigarrow$   $\omega_u =$  connection 1-form,  $\mathfrak{gl}(r)$ -valued on  $u$

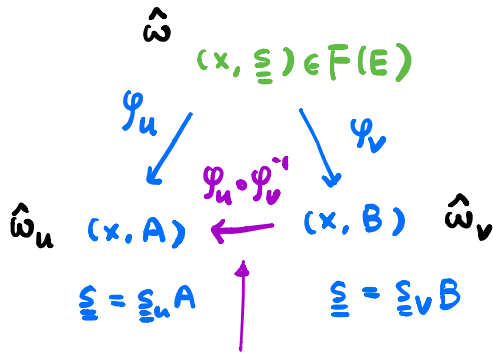
$M \ni u, \omega_u$  Idea: Define  $\hat{\omega}_u := \hat{\pi}^*(\omega_u)$ , 1-form,  $\mathfrak{gl}(r)$ -valued on  $\hat{\pi}^{-1}(u)$

Q: well-defined? "invariance under coord. change"?  $\checkmark$

Well-definedness: Suppose we have another local frame

$\underline{s}_v := (s_1^v, \dots, s_r^v)$  of  $E$  over  $V \subseteq M$  s.t.  $U \cap V \neq \emptyset$

Claim:  $\hat{\pi}^*(\omega_u) = \hat{\pi}^*(\omega_v)$  on  $\hat{\pi}^{-1}(U \cap V) \subseteq F(E)$



Locally,

$$\hat{\omega}_u = \underbrace{A^{-1}dA}_{\text{tangent to fiber}} + \underbrace{A^{-1}\omega_u A}_{\text{tangent to } M} \quad \text{in } \mathcal{F}_u\text{-coord.}$$

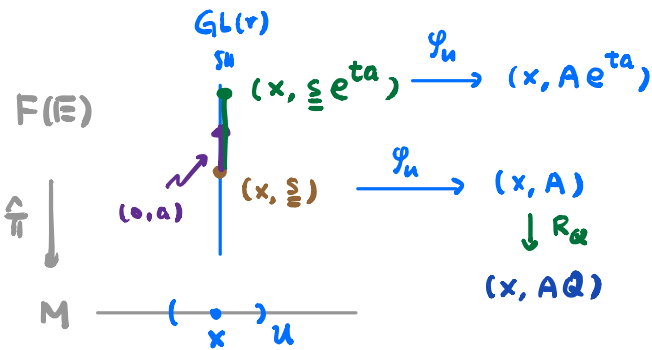
$$\hat{\omega}_v = B^{-1}dB + B^{-1}\omega_v B \quad \text{in } \mathcal{F}_v\text{-coord.}$$

Need to check:  $(\varphi_u \circ \varphi_v^{-1})^* \hat{\omega}_u = \hat{\omega}_v$

$$\begin{aligned} (\varphi_u \circ \varphi_v^{-1})^* \hat{\omega}_u &= (CB)^{-1}d(CB) + (CB)^{-1}\omega_u(CB) \\ &= B^{-1}(C^{-1}dC)B + B^{-1}C^{-1}CdB + B^{-1}C^{-1}\omega_u C B \\ &= B^{-1}dB + B^{-1}(C^{-1}dC + C^{-1}\omega_u C)B = \hat{\omega}_v. \end{aligned}$$

Claim:  $\hat{\omega}$  satisfies (1) & (2)

(1)  $\hat{\omega}(0, a) = a \quad \forall (0, a) \in T_{(x, \underline{s})}F(E)$  ✓



Recall:  $\hat{\omega}_u = A^{-1}dA + A^{-1}\omega_u A$

At  $(x, \underline{s})$ .

$$\hat{\omega}_{(0, a)} = \hat{\omega}_{u, (x, A)}(0, Aa) = A^{-1}(Aa) = a$$

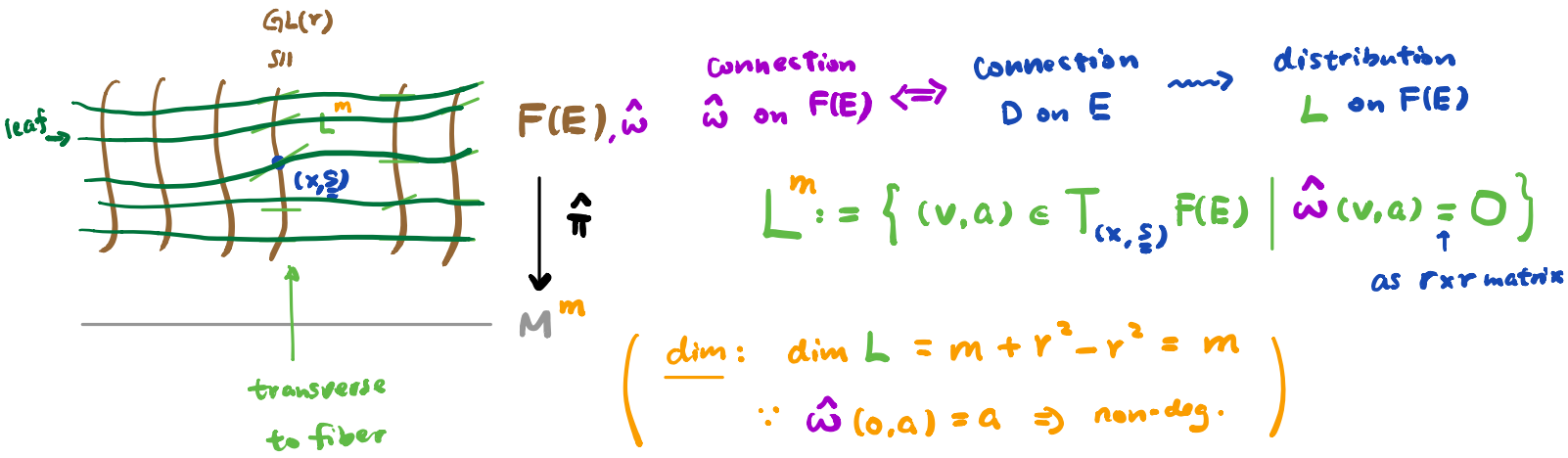
(2)  $\forall Q \in GL(r), R_Q^* \hat{\omega} = Q^{-1} \hat{\omega} Q$

Recall:  $\hat{\omega}_u = A^{-1}dA + A^{-1}\omega_u A$  locally

$$\begin{aligned} R_Q^*(\hat{\omega}_u) &= (AQ)^{-1}d(AQ) + (AQ)^{-1}\omega_u(AQ) \\ &= Q^{-1}(A^{-1}dA + A^{-1}\omega_u A)Q = Q^{-1}\hat{\omega}_u Q \end{aligned}$$

↑  $Q$  is fixed

This Thm. provides a different point of view to understand "connections".



Proposition: Locally, TFAE:

(1)  $D$  is flat (i.e.  $\Omega \equiv 0$ )

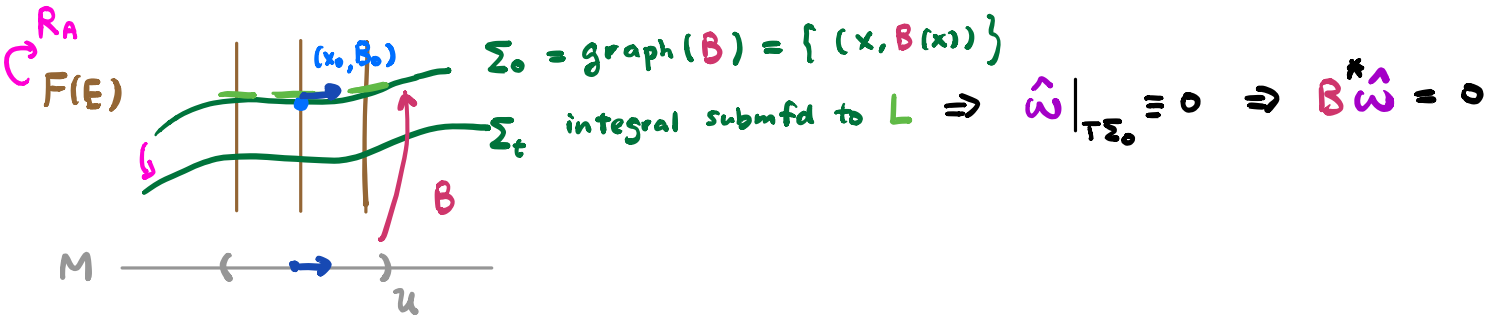
$\Leftrightarrow$  (2)  $L$  is integrable

$\Leftrightarrow$  (3)  $\exists B: \mathcal{U} \rightarrow F(E)$  s.t.  $B^*(\hat{\omega}) = 0$

i.e.  $\exists$  parallel local frame  $\tilde{\Sigma} = (\tilde{S}_1, \dots, \tilde{S}_r)$ .

Proof by Pictures:

(2)  $\Leftrightarrow$  (3):



(1)  $\Leftrightarrow$  (2): Recall:  $\hat{\Omega} = d\hat{\omega} + \hat{\omega} \wedge \hat{\omega}$

$$v, w \in L \Rightarrow d\hat{\omega}(v, w) = \underbrace{\hat{\Omega}(v, w)}_{\text{flat}} = 0$$

dual Frobenius thm.

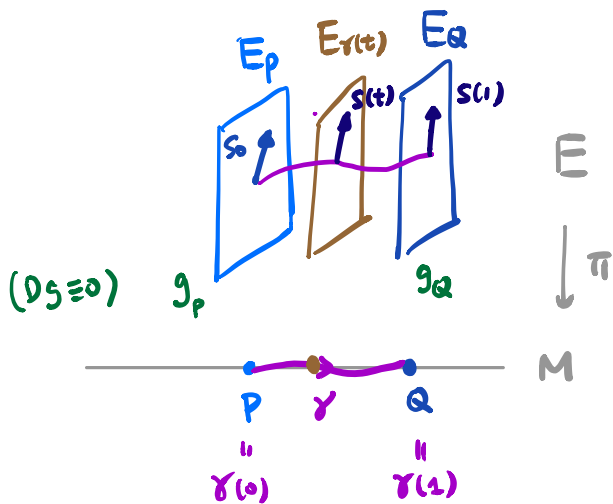
$\downarrow$   
 $\Leftrightarrow L$  integrable

\_\_\_\_\_  $\square$

# Parallel Transport

Given a connection  $D$  on  $\pi: E \rightarrow M$ .  $\leadsto$  defines covariant derivative

$$D_x S \text{ on } s \in \mathcal{P}(E)$$



The parallel transport along  $\gamma$ :

$$P_{P,\gamma}^0: E_P \xrightarrow{\cong} E_Q$$

linear isomorphism  
(Dg=0  $\Rightarrow$  isometry)

$$\begin{matrix} \downarrow \\ S_0 \end{matrix} \longmapsto \begin{matrix} \downarrow \\ S(1) \end{matrix}$$

where  $S: [0,1] \rightarrow E$  is the sol<sup>n</sup> to

$$(\#) \begin{cases} D_\gamma S = 0 \text{ along } \gamma \\ S(0) = S_0 \end{cases}$$

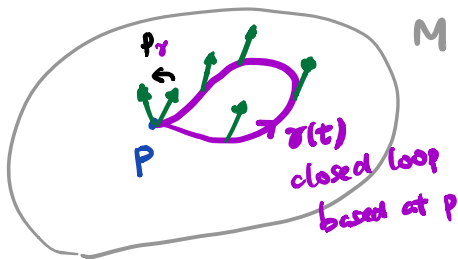
1st order ODE linear system

Locally:  $(\#): \begin{cases} \frac{da^\alpha}{dt} + T_{i\alpha}^\beta(x(t)) \frac{dx^i}{dt} a^\alpha = 0, \quad \alpha=1, \dots, r \\ a^\alpha(0) = a_0^\alpha \end{cases}$

← unknown →

where  $\gamma'(t) = \sum_i \frac{dx^i}{dt} \frac{\partial}{\partial x^i}(\gamma(t))$ ;  $S(t) = \sum_{\alpha=1}^r a^\alpha(t) S_\alpha(\gamma(t))$ .

this leads to the notion of **holonomy group**:



$$P_\gamma: E_P \rightarrow E_P \in GL(E_P)$$

Define:  $H_P(0) := \{ P_\gamma \mid \gamma \text{ loop at } P \} \subseteq GL(E_P)$

Some Remarks:

(i)  $H_P \cong H_Q \quad \forall P, Q \in M$  (up to conjugate)

(ii)  $Dg \equiv 0 \Rightarrow H_P \subseteq O(E_P)$

(iii)  $D$  flat  $\Leftrightarrow H_P = \{1\}$   
locally

# Affine Connections (Chern §4.2)

Def<sup>n</sup>: A connection  $D$  on the tangent bundle  $TM$  is called an **affine connection**.

Note: • general theory of connections on vector bundle applies.

• But often "more non-linear"

$$E \ni (x^1, \dots, x^m, s_1, \dots, s_r)$$

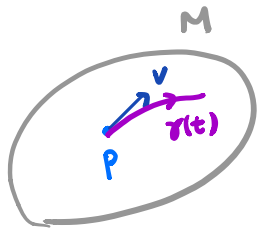
$$\downarrow \\ M \ni (x^1, \dots, x^m)$$

$$TM \ni (x^1, \dots, x^m, \frac{\partial}{\partial x^1}, \dots, \frac{\partial}{\partial x^m})$$

$$\downarrow \\ M \ni (x^1, \dots, x^m)$$

Geodesic eq<sup>n</sup>:  $D_Y \gamma' \equiv 0$  where  $\gamma$  is a parametrized curve on  $M$  (called geodesic)

In local coord, this is



$$\frac{d^2 x^k}{dt^2} + \sum_{j,k=1}^m T_{ij}^k(x(t)) \frac{dx^i}{dt} \frac{dx^j}{dt} = 0$$

2<sup>nd</sup> order  
non-linear ODE  
system

(short-time existence  
& uniqueness)

Def<sup>n</sup>: Given an affine connection  $D$  on  $TM$ , define its **torsion** to be

$$T: \mathfrak{X}(M) \times \mathfrak{X}(M) \longrightarrow \mathfrak{X}(M)$$

$$T(X, Y) := D_X Y - D_Y X - [X, Y]$$

Easy Facts:

- $T$  is tensorial in both  $X$  and  $Y$
- $T$  is skew-symmetric (ie.  $T(Y, X) = -T(X, Y)$ )

$$\Rightarrow T \in T(\wedge^2 T^*M \otimes TM)$$

Alternatively, one can look at the

"tautological 1-form":  $\theta \in T^*(T^*M \otimes TM)$

1-form

$$\theta(x) := x$$

ie.  $\theta = id_{TM}$

Prop:

$$T = D\theta$$

where  $D: T(\wedge^1 T^*M \otimes TM) \rightarrow T(\wedge^2 T^*M \otimes TM)$

Proof: Check locally,  $e_1, \dots, e_m$  basis for  $TM$ ,  $\theta^1, \dots, \theta^m$  dual basis for  $T^*M$ .

$$\theta = \sum_{i=1}^m \theta^i \otimes e_i$$

$$\Rightarrow D\theta = \sum_{i=1}^m \left( d\theta^i \otimes e_i - \theta^i \wedge \underbrace{D e_i}_{\sum_{j=1}^m \omega^j e_j} \right) = \sum_{i=1}^m \left( \underbrace{d\theta^i - \sum_{j=1}^m \theta^j \wedge \omega^j}_{\text{2-form}} \right) \otimes e_i$$

Claim:

$$T = d\theta + \omega \wedge \theta$$

Pf claim:  $(d\theta + \omega \wedge \theta)(x, \gamma)$

$$= \sum_{i=1}^m \left[ d\theta^i(x, \gamma) + \sum_j \omega^j \wedge \theta^j(x, \gamma) \right] e_i$$

$$= \sum_{i=1}^m \left[ \frac{x(\theta^i(\gamma)) - \gamma(\theta^i(x)) - \theta^i([x, \gamma])}{\text{inv. formula for } d\theta^i} + \sum_j (\omega^j(x) \theta^j(\gamma) - \omega^j(\gamma) \theta^j(x)) \right] e_i$$

$$= \sum_{i=1}^m \left[ \theta^i(D_x \gamma) - \theta^i(D_\gamma x) - \theta^i([x, \gamma]) \right] e_i$$

$$= \sum_{i=1}^m \left[ \theta^i(T(x, \gamma)) \right] e_i = T(x, \gamma).$$

Def<sup>n</sup>:  $D$  is torsion-free iff  $T \equiv 0$  (ie.  $T_{ij}^k = T_{ji}^k$ )

Def<sup>n</sup>:  $D, D'$  are affine equivalent

iff  $D, D'$  has the same parametrized geodesics

Note: Given an arbitrary affine connection  $D$  on  $TM$ .

it may not be torsion-free.

But,  $\exists D'$  affine equivalent to  $D$ , and  $D'$  is torsion-free

Why: Ex:  $D'_x Y := D_x Y - \frac{1}{2} T(x, Y)$  [ie.  $T'_{ij}{}^k = \frac{1}{2} (T_{ij}{}^k + T_{ji}{}^k)$ ]

Prop: (Existence of normal coordinates at  $p \in M$ )

Let  $D$  be an affine connection on  $TM$ .

$T(p) = 0$  at some  $p \in M$   $\Leftrightarrow \exists$  local coord.  $x^1, \dots, x^m$  of  $M$ , centered at  $p$ ,  
st.  $D_{\partial_i} \partial_j (p) = 0 \quad \forall i, j = 1, \dots, m$

"Sketch of Proof":  $\Leftarrow$  trivial

$\Rightarrow$  (Similar to the proof of general  $E \rightarrow M$ )

Ex:  $\tilde{T}_{ij}{}^k = \sum_p \left( \frac{\partial \tilde{x}^k}{\partial x^p} \frac{\partial^2 x^p}{\partial \tilde{x}^i \partial \tilde{x}^j} \right) + \sum_{p, r, s} \left( \frac{\partial \tilde{x}^k}{\partial x^p} \frac{\partial x^p}{\partial \tilde{x}^j} \frac{\partial x^r}{\partial \tilde{x}^i} \right) T_{rs}{}^p$

define:  $x^k = \tilde{x}^k - \frac{1}{2} T_{ij}{}^k(o) \tilde{x}^i \tilde{x}^j$

Def<sup>n</sup>:  $(M^m, g)$  Riemannian manifold

is a  $C^\infty$  manifold  $M^m$  with a fiber metric  $g$  on  $TM$   
(positive definite)

Remark:  $g$  only non-degenerate  $\rightarrow$  pseudo-Riemannian

Fundamental Thm of Riem. Geometry

Given a Riem. mfd  $(M, g)$ .  $\exists!$  connection  $D$  on  $TM$  st.

- |                 |                   |   |
|-----------------|-------------------|---|
| ① $Dg \equiv 0$ | metric-compatible | } "Levi-Civita" / "Riemannian" connection |
| ② $T \equiv 0$  | torsion-free      |   |